

CHARACTERIZATION OF NONLINEAR NEURON RESPONSES

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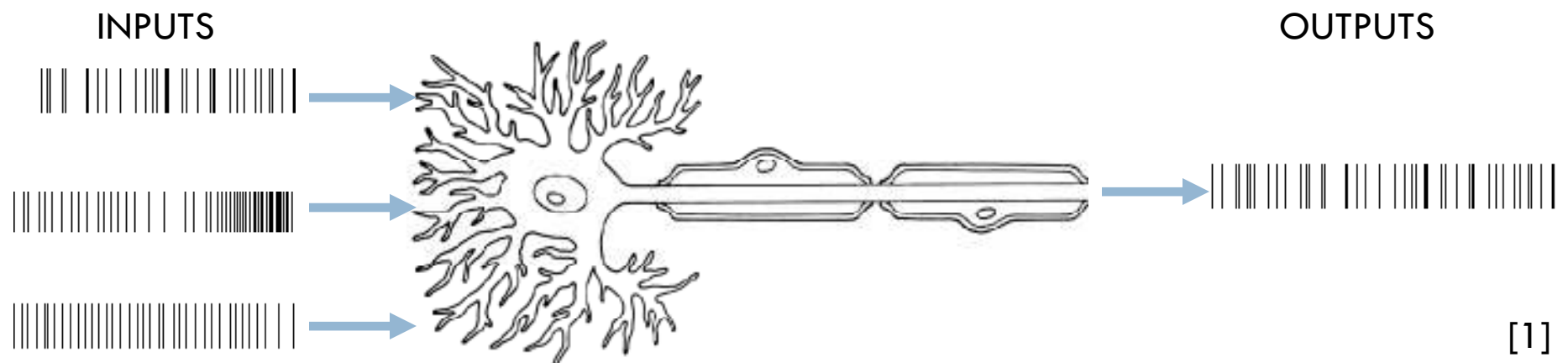
Applied Mathematics and Scientific Computation (AMSC)

Biological Sciences Graduate Program (BSI)

AMSC 663 Project Proposal Presentation

Background

- The human brain contains 100 billion neurons
- These neurons process information nonlinearly, thus making them difficult to study

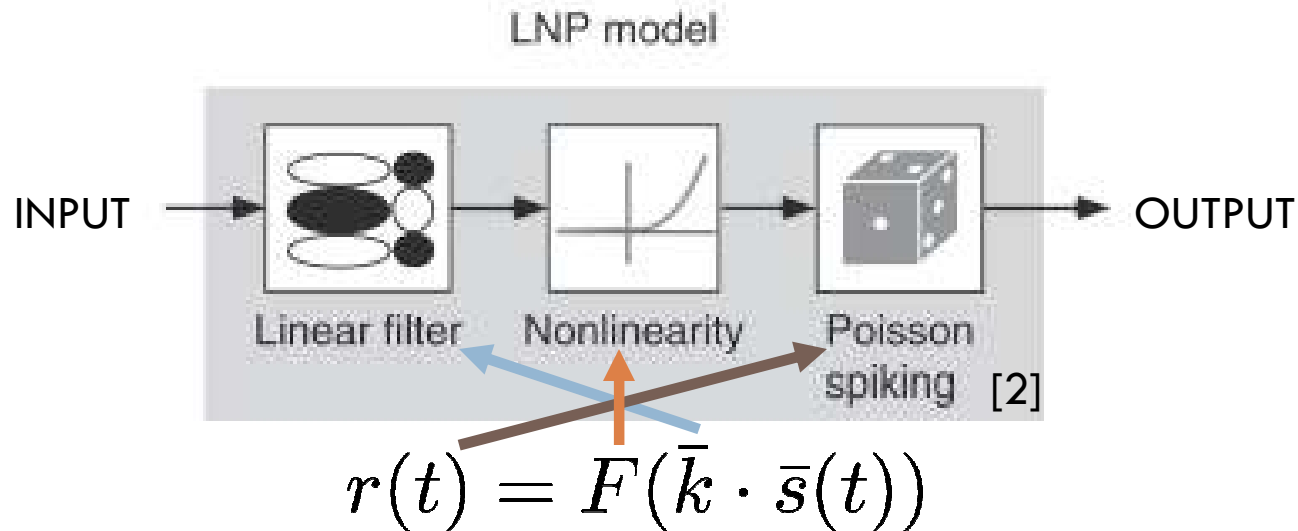


- Given the inputs and the outputs, how can we model the neuron's computation?

The Models

- Many models of increasing complexity have been developed
- The models I will be implementing are based on statistics
 - ▣ Linear Models – Linear Nonlinear Poisson (LNP) Model
 1. LNP using Spike Triggered Average (STA)
 2. LNP using Maximum Likelihood Estimates – Generalized Linear Model (GLM)
 3. Spike Triggered Covariance (STC)
 - ▣ Nonlinear Models
 4. Generalized Quadratic Model (GQM)
 5. Nonlinear Input Model (NIM)

The Models - LNP



□ Knowns

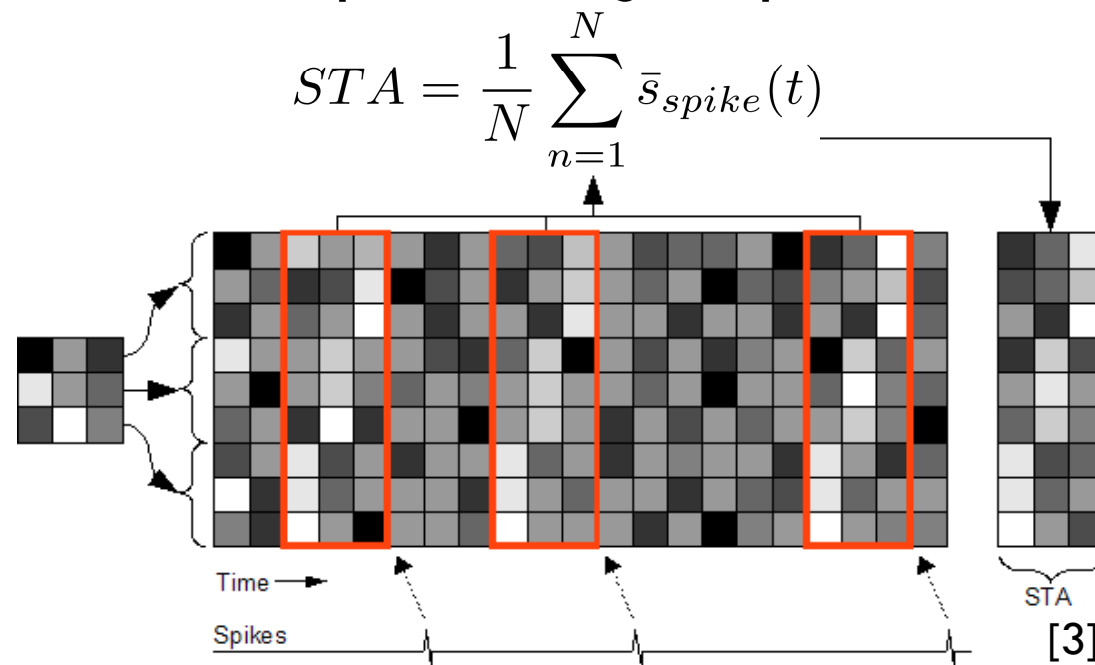
- $\bar{s}(t)$ is the stimulus vector
- Spike times

□ Unknowns

- \bar{k} is a linear filter, defines the neuron's stimulus selectivity
- F is a nonlinear function
- $r(t)$ is the instantaneous rate parameter of a non-homogeneous Poisson process

The Models - LNP-STA¹

- The STA is the average stimulus preceding a spike in the output, where N is the number of spikes and $\bar{s}_{spike}(t)$ is the set of stimuli preceding a spike



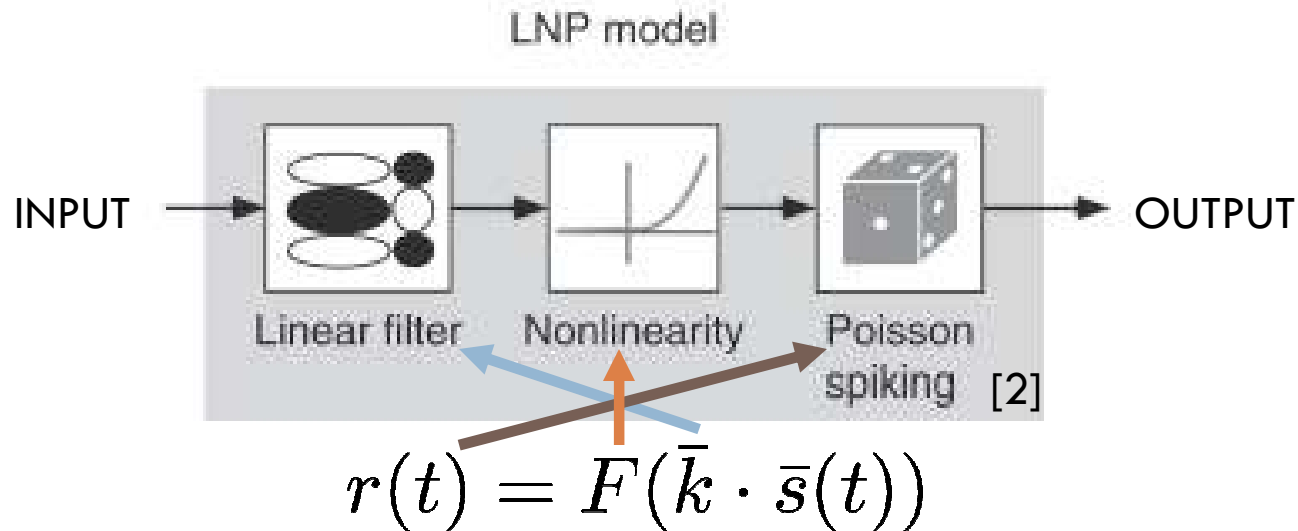
1. Chichilnisky, E.J. (2001) A simple white noise analysis of neuronal light responses.

[3] http://en.wikipedia.org/wiki/Spike-triggered_average

The Models - LNP-STA

- It can be shown that the STA is proportional to the linear filter \bar{k}
- Though it is possible to fit a parametric form of the nonlinear function, the more common approach is to bin the values of $\bar{k} \cdot \bar{s}(t)$ and plot average spike count for each bin based on the stimulus and spike data (histogram method).
- The Algorithm:
 - ▣ Calculate the STA to find \bar{k}
 - ▣ Use the stimulus and the filter for the histogram method to estimate F discretely

The Models - LNP



□ Knowns

- $\bar{s}(t)$ is the stimulus vector
- Spike times

□ Unknowns

- \bar{k} is a linear filter, defines the neuron's stimulus selectivity
- F is a nonlinear function
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The Models - LNP-GLM²

- Now we will approximate the linear filter using the Maximum Likelihood Estimate (MLE)
- A likelihood function $\mathcal{L}(\theta)$ is the probability of an outcome Y given a probability density function with parameter θ
- The LNP model uses the Poisson distribution

$$P(Y|\theta) = \prod_t \frac{(r(t)\Delta)^{y_t}}{y_t!} e^{-r(t)\Delta}$$

where Y is the vector of spike counts binned at a resolution Δ

- We want to maximize a log-likelihood function

$$\mathcal{L} = \sum_{t=spike} \log(r(t)) - \Delta \sum_t r(t)$$

The Models - LNP-GLM

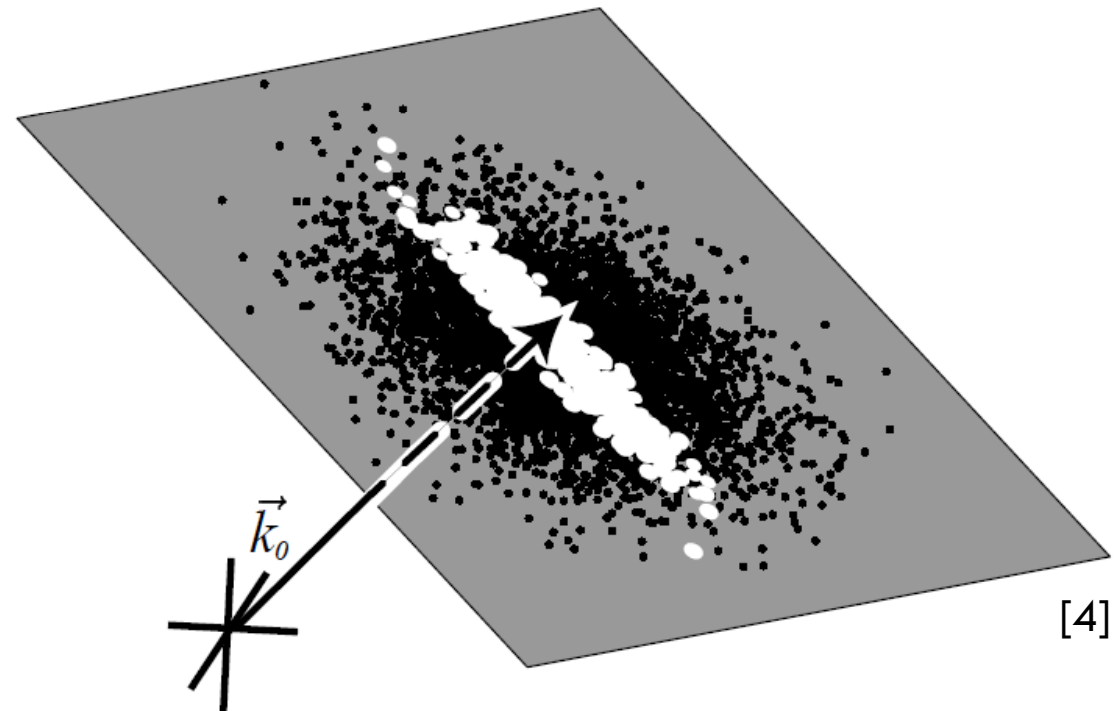
- The Maximum Likelihood Estimate maximizes the probability of spiking as a function of the model parameters when the actual data shows a spike, and minimizes it otherwise.
- Can employ likelihood optimization methods to obtain maximum likelihood estimates for linear filter \bar{k}
- If we make some assumptions about the form of the nonlinearity F , the likelihood function has no non-global local maxima – gradient ascent!
 - $F(u)$ is convex in u
 - $\log(F(u))$ is concave in u
- Regularizing estimated linear filter can reduce noise effects
 - Applies penalty for complexity

The Models - LNP-GLM

- The Algorithm:
 - ▣ Assume a form of F and get the corresponding log-likelihood function
 - ▣ Depending on the resulting function, find the MLE by analytical or numerical means

The Models - STC³

- Spike Triggered Covariance (STC) analysis is a way to identify a feature subspace that affects a neuron's response.
- Find excitatory and suppressive directions



3. Schwartz, O. et al. (2006) Spike-triggered neural characterization.

[4] <http://books.nips.cc/papers/files/nips14/NS14.pdf>

The Models - STC

$$STC = \frac{1}{N-1} \sum_{n=1}^N (\bar{s}_{spike}(t) - STA)(\bar{s}_{spike}(t) - STA)^T$$
$$C = \frac{1}{N-1} \sum_{n=1}^N \bar{s}_{spike}(t) \bar{s}_{spike}(t)^T$$

- The smallest eigenvalues associated with $STC - C$ correspond to inhibitory eigenvectors in the stimulus space; we will just use the smallest for a “suppressive” filter.

The Models - STC

- The model then becomes

$$r(t) = F(\bar{k}_e \cdot \bar{s}(t), \bar{k}_s \cdot \bar{s}(t))$$

- Knowns

- $\bar{s}(t)$ is the stimulus vector
- Spike times

- Unknowns

- \bar{k}_e is the excitatory filter
- \bar{k}_s is the suppressive filter
- F is a nonlinear function
- $r(t)$ is the instantaneous rate parameter of a non-homogeneous Poisson process

The Models - STC

- Again, we could try to fit the nonlinearity parametrically, but using the histogram method is fine if we are just using two filters, with bin values coming from $\bar{k}_e \cdot \bar{s}(t)$ and $\bar{k}_s \cdot \bar{s}(t)$
- The Algorithm:
 - ▣ Calculate the STA to find \bar{k}_e
 - ▣ Calculate the eigenvectors/values of $STC - C$
 - ▣ Use eigenvector associated with smallest eigenvalue to find \bar{k}_s
 - ▣ Use the stimulus and the filter for the histogram method to estimate F discretely

The Models - Nonlinear Models

- We can extend these models even further by introducing nonlinearities in the input. The general form is:

$$r(t) = F(f_1(\bar{k}_1 \cdot \bar{s}(t)), \dots, f_n(\bar{k}_n \cdot \bar{s}(t)))$$

where the f_i 's can be any nonlinear functions.

- Perhaps we should start with something easier first...
- Assuming that the input is a *sum* of one-dimensional nonlinearities makes parameter fitting much nicer

The Models - GQM⁴

- A particular choice of this sum of nonlinearities gives us the Generalized Quadratic Model:

$$r(t) = F\left(\frac{1}{2}\bar{s}(t)^T C \bar{s}(t) + \bar{b}^T \bar{s}(t) + a\right)$$

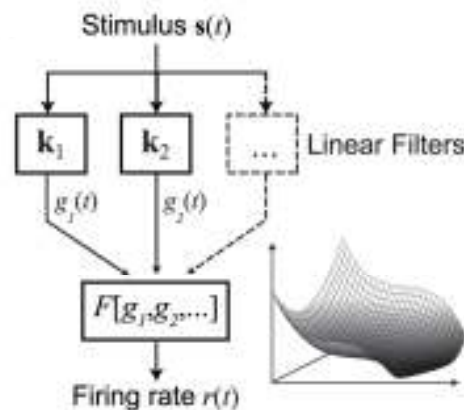
- Knowns
 - $\bar{s}(t)$ is the stimulus vector
 - Spike times
- Unknowns
 - matrix C
 - vector \bar{b}
 - scalar a
 - F is a nonlinear function
 - $r(t)$ is the instantaneous rate parameter of a non-homogenous Poisson process

The Models - GQM

- Even though we are no longer dealing with the GLM, in practice if we choose a form of F that preserves concavity of the log-likelihood, estimating the parameters using MLE will be tractable
- Functions commonly used are $\exp(u)$ and $\log(1 + \exp(u))$
- The Algorithm:
 - ▣ Write down the log-likelihood function
 - ▣ Use optimization to find MLE, assuming one of the above forms for F

The Models - NIM⁵

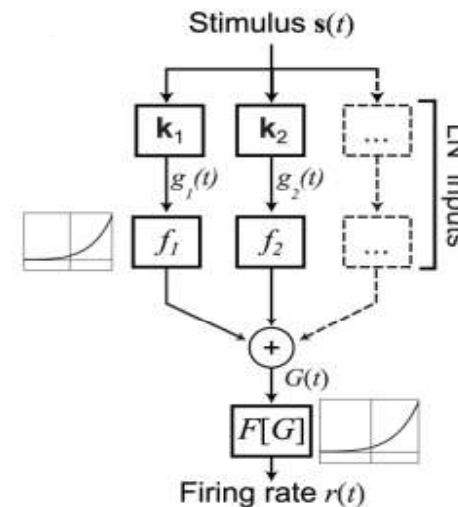
LINEAR NONLINEAR MODEL



$$r(t) = F(\bar{k}_1 \cdot \bar{s}(t), \bar{k}_2 \cdot \bar{s}(t), \dots)$$

NONLINEAR INPUT MODEL

[5]



$$r(t) = F(f_1(\bar{k}_1 \cdot \bar{s}(t)), f_2(\bar{k}_2 \cdot \bar{s}(t)) \dots)$$

- The Nonlinear Input Model (NIM) defines the neuron's processing as a sum of nonlinear inputs
- Allows for rectification of inputs due to spike-generation from the input neuron

The Models - NIM

$$r(t) = F \left(\sum_i w_i f_i(\bar{k}_i \cdot \bar{s}(t)) \right)$$

- Knowns
 - $\bar{s}(t)$ is the stimulus vector
 - Spike times
- Assumptions
 - $F(u) = \alpha \log[1 + e^{\beta(u-\theta)}]$
 - f_i 's are rectified linear functions
- Unknowns
 - \bar{k}_i 's are the linear filters
 - w_i 's will be +/-1
 - f_i 's are nonlinear functions
 - F is a nonlinear function
 - $r(t)$ is the instantaneous rate parameter of a non-homogenous Poisson process

The Models - NIM

- The Algorithm
 - ▣ Write down the log-likelihood function
 - ▣ Use optimization to find MLE, assuming one of the above forms for F
 - ▣ Regularization will allow us to incorporate prior knowledge about the parameters

Implementation and Data

- Parameter fitting will be implemented on an Intel Core 2 Duo with 3 GB of RAM
- Programming language will be MATLAB
- Data
 - ▣ Initial work will be done using data from a Lateral geniculate nucleus (LGN) neuron (visual system)
 - ▣ simulated data from other neurons in the visual system
 - ▣ Data can be found at <http://www.clfs.umd.edu/biology/ntlab/NIM/>

Validation

- Use stimulus data $\bar{s}(t)$ and response data $\bar{r}(t)$ to construct the model, i.e. find the model parameters
- Use stimulus data $\bar{s}(t)$ and the model to create new response data $\bar{r}_{model}(t)$
- Now use $\bar{s}(t)$ and $\bar{r}_{model}(t)$ to generate a new model
- Check to see how closely the parameters of the new model and the original model agree

Testing

- Use k-fold cross-validation on the log-likelihood of the model, LL_x , with the log-likelihood of the “null” model, LL_0 , subtracted.
- Measure the ‘predictive power’ of the model by comparing the predicted model output to the measured output:
 - ‘fraction of variance explained’

$$FVE = 1 - \frac{MSE(F)}{Var(\bar{r}_{measured}(t))}$$

- Use early models (i.e. LNP) to compare results of later models (i.e. NIM)

Project Schedule and Milestones

- PHASE I – September through December
 - Write project proposal (September)
 - Implement and validate the LNP model (October)
 - Develop software to validate models (October)
 - Implement and validate the GLM with regularization (November-December)
 - Complete mid-year progress report (December)
- PHASE II – January through May
 - Implement and validate the STC and GQM (January-February)
 - Implement and validate the NIM with linear rectified upstream functions (March)
 - Develop software to test all models (April)
 - Complete final report and presentation
- If time permits...
 - Fit the nonlinear upstream functions of the NIM using basis functions
 - Extend models to be used for more diverse stimulus types
 - Use the NIM to model small networks of neurons

Deliverables

- Implemented MATLAB code for all of the models (LNP-STA, LNP-GLM, STC, GQM, NIM)
- Documentation of code
- Results of validation and testing for all of the models
- Mid-year presentation
- Final report
- Final presentation

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Figures

1. http://msjensen.cehd.umn.edu/webanatomy_archive/Images/Histology/
2. <http://www.sciencedirect.com/science/article/pii/S0079612306650310>
3. http://en.wikipedia.org/wiki/Spike-triggered_average
4. <http://books.nips.cc/papers/files/nips14/NS14.pdf>
5. McFarland, J.M., Cui, Y., and Butts, D.A. (2013) Inferring nonlinear neuronal computation based on physiologically plausible inputs. PLoS Computational Biology.